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Appendix 3 – analysis of concrete in programs GEO4 according to IS 456

1. Materials, coefficients, notation

The following notation for material parameters is used:

f_{ck} – characteristic cube compressive strength of concrete,
 f_{cd} – design strength of concrete in compression,
 f_{ctk} – characteristic strength of concrete in tension,
 f_{ctd} – design strength of concrete in tension,
 f_{yk} – characteristic strength of steel,
 f_{yd} – design strength of steel in tension.

The characteristic compressive strength of concrete is the basic input parameter given by the class of concrete – it serves to derive the remaining coefficients of reliability.

$$f_{cd} = 0,67 \frac{f_{ck}}{1,5}$$

$$f_{ctk} = 0,7 \sqrt{f_{ck}}$$

$$f_{ctd} = 0,67 \frac{f_{ctk}}{1,5}$$

$$E_c = 5000 \sqrt{f_{ck}}$$

$$f_{yd} = \frac{f_{yk}}{1,15}$$

The most common notation for geometrical parameters:

b – cross-section width,
 h – cross-section depth,
 d – effective height of cross-section,
 z – lever arm (arm of internal forces).

All computations are carried out according to the theory of limit states.

2. Verification of RC rectangular cross-section under the bending moment(programs Cantilever wall, Spread footing, Abutment)

The cross-section is rectangular, reinforced on one side and loaded by the bending moment M .

The permissible moment for a given area of reinforcements A_s reads:

$$M_{rd} = b \cdot F_c \cdot (d - 0,42x)$$

$$F_c = 0,36 \cdot f_{ck} \cdot x$$

$$x = \frac{A_s \cdot f_{yd}}{b \cdot 0,36 \cdot f_{ck}}$$

The program further checks whether the location of neutral axis x is less than the limit location of neutral axis x_{max} given by:

$$x_{max} = 0.53d \text{ - for steel Fe 250}$$

$$x_{max} = 0.48.d \text{ - for steel Fe 400}$$

$$x_{max} = 0.46.d \text{ - for steel Fe 500}$$

The computed degree of reinforcement is checked using the following expressions:

$$\rho_{min} \leq \rho \leq \rho_{max}$$

where

$$\rho = \frac{A_s}{bh}$$

$$\rho_{min} = \frac{0,85}{f_{yk}}$$

$$\rho_{max} = 0.04$$

3. Verification of spread footing for punching shear (program Spread footing)

The critical section loaded in shear (U_{cr}) is distant from the column edge by one half of the footing thickness. It is loaded by the prescribed moments M_x , M_y , and by the shear force V_r , provided by:

$$V_r = \frac{QA_t}{A}$$

where

- A - area of footing,
- Q - assigned vertical force developed in column,
- A_t - hatched area in fig.

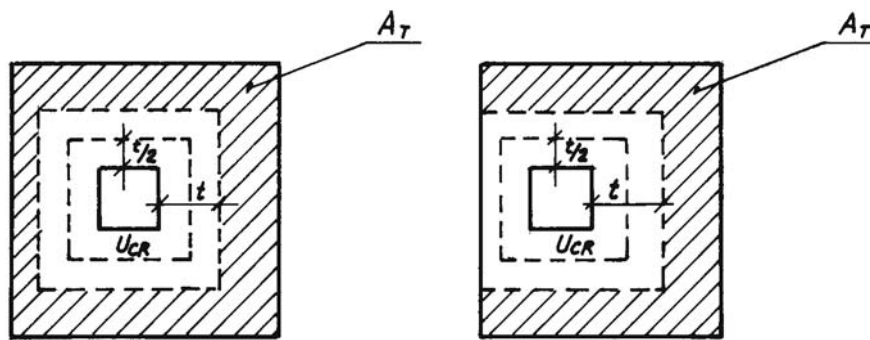


Fig. Dimensioning of shear reinforcement area A_t

The program computes the maximum shear force V developed in the critical section, the shear force transmitted by concrete with no shear reinforcement V_c , and the maximal allowable force V_{max} .

$$V_c = \tau_{rd} \cdot k_s \cdot h$$

$$V_{max} = \tau_{c,max} \cdot h$$

where

$$\tau_c = 0,25 \sqrt{f_{cTk}}$$

$$k_s = \text{Min}\left(0,5 + \frac{c_x}{c_y}; 1\right)$$

c_x, c_y are dimensions of footing column, $\tau_{c,max}$ is the maximum allowable shear stress in concrete listed in table 20 of the IS 456 standard.

For $V < V_c$ no shear reinforcement is needed.

For $V > V_c$ and $V_c < V_{max}$ it is necessary to design shear reinforcement. The permissible shear force is given by:

$$V_{rd3} = \frac{1}{2}V_c + V_{us}$$

$$V_{us} = \frac{\sum 0,87 \cdot A_{us} \cdot f_{yd} \cdot \sin \alpha}{u}$$

where

- u - critical cross-section span,
- α - angle of crooks,
- A_{us} - overall area of crooks in footing.

For $V_c > V_{max}$ the shear reinforcement cannot be designed. It is therefore necessary to increase the cross-section depth.

4. Verification of cross-sections made from plain concrete (programs Gravity wall, Abutment)

The cross-section is rectangular, loaded by the bending moment M , normal force N (applied in the cross-section centroid) and by the shear force V .

Strength of concrete cross-section loaded by the bending moment is given by:

$$M_{rd} = \frac{bh^2}{6} f_{ctd}$$

The shear strength is provided by

$$V_{rd} = \tau_c . b . h$$

where τ_c is the design value of stress in concrete obtained from table 19 of the IS456 standard for degree of longitudinal reinforcement $\rho=0$.

Strength of concrete cross-section subject to the combination of bending moment and normal force with eccentricity e is derived from the following expressions:

$$e < 0,9a_{gc} \Rightarrow N_{rd} = x . f_{cd}$$

$$e > 0,9a_{gc} \Rightarrow N_{rd} = \frac{b . h . f_{ctd}}{\frac{6e}{h} - 1}$$

where

$$x = h - 2e$$

$$e = \frac{abs(M)}{N}$$

$$a_{gc} = \frac{h}{2}$$

5. Verification of circular RC cross-section(program Pile)

The program verifies a reinforced concrete pile using the method of limit deformation. The maximum allowable strain of concrete in compression is 0,002 - 0.0035.

The degree of reinforcement is checked using the formula:

$$\rho_{\min} \leq \rho \leq \rho_{\max}$$

where

$$\rho = \frac{2A_s}{\pi d^2}$$

$$\rho_{\min} = \frac{0,85}{f_{yk}}$$

$$\rho_{\max} = 0.04$$

where

A_s - reinforcement area
 d - pile diameter

6. Design of longitudinal reinforcement for plates (program Plate-Reinforcement)

The design of reinforcement is performed for loading caused by the bending moment M_{sd} . The program provides the required area of tensile and compressive (if needed) reinforcement. It takes into account conditions for the minimum and maximum degree of reinforcement in a given cross-section.

First, the program determines the location of neutral axis as:

$$x = \frac{d - \sqrt{d^2 - \frac{1.68 M_{rd}}{0.36 b f_{ck}}}}{0.84} ,$$

Providing the location of neutral axis is less than the allowable one ($x < x_{max}$), the program determines the area of tensile reinforcement A_{st} from the expression:

$$A_s = \frac{0.36 b f_{ck}}{f_{yd}} x .$$

Providing the location of neutral axis is greater than the allowable one ($x > x_{max}$), the program determines the areas of both compressive (A_{sc}) and tensile (A_{st}) reinforcement from the expressions:

$$A_{sc} = \frac{M - F_{c,max} (d - 0.42 \cdot x_{max})}{f_{yd} \cdot z}$$

$$A_{st} = \frac{F_{c,max} + A_{sc} \cdot f_{yd}}{f_{yd}}$$

$$F_{c,max} = x_{max} \cdot b \cdot f_{cd}$$

The limit location of neutral axis is found from:

$$x_{max} = 0.53d \quad \text{- for steel Fe 250}$$

$$x_{max} = 0.48 \cdot d \quad \text{- for steel Fe 400}$$

$$x_{max} = 0.46 \cdot d \quad \text{- for steel Fe 500}$$

The minimum area of tensile and compressive reinforcement, respectively, is provided by:

$$A_{st,min} = b.h\rho_{t,min}$$

$$\rho_{t,min} = \frac{0,85}{f_{yk}}$$

$$A_{sc,min} = b.h\rho_{c,min}$$

$$\rho_{c,min} = 0,0015$$

If the maximum degree of tensile reinforcement ($\rho_{t,max}=0.04$) or compressive reinforcement ($\rho_{t,max}=0.08$), respectively, is exceeded, the program informs the user that the longitudinal reinforcement cannot be designed for a given cross-section.

7. Design of shear reinforcement for plates (program Plate-Reinforcement)

The program allows determination of the required amount of shear reinforcement form by stirrups and crooks, respectively.

First, the program computes the limit shear force in a given section – the shear force transmitted by concrete V_c and the maximum allowable shear force V_{max} .

$$V_c = \tau_c \cdot b \cdot h$$

$$V_{max} = \tau_{c,max} \cdot b \cdot h$$

where values $\tau_c, \tau_{c,max}$ are obtained from tables 19 and 20 of the IS 456 standard.

No shear reinforcement is needed providing the shear force V is less than the shear force transmitted by concrete V_c .

If the shear reinforcement V is greater than the maximum allowable shear force V_{max} , then the shear force cannot be designed and it is necessary to increase the plate dimensions.

The required area of shear reinforcement formed by stirrups per 1 m² is found from:

$$A_{sv} = \frac{(V - V_c)}{0,87 \cdot f_{ywd} \cdot d}$$

8. Verification of RC rectangular cross-section under the bending moment and normal compression force (program Abutment)

The cross-section is rectangular, reinforced on one side and loaded by the bending moment M and normal compression force.

The location of neutral axis is given by:

$$x = 0,5.h - e + \sqrt{(0,5.h - e)^2 + \frac{F_s \cdot (z_s + e)}{0,5.b.f_{cd}}}$$

where

$$e = \frac{M}{N}$$

$$F_s = f_{yd} \cdot A_s$$

$$z_s = d - 0,5.h$$

For $x < x_{max}$ permissible normal force is given by:

$$N_{rd} = -F_s + x.b.f_{cd}$$

For $x > x_{max}$ the corrected location of neutral axis is found from:

$$x = x_{max} + abs(M_3 \frac{0,8.d - x_{max}}{M_4 - M_3})$$

$$M_3 = F_s \cdot (e + z_s) - x_{max} \cdot b \cdot f_{cd}$$

$$M_4 = -0,8.d \cdot x_{max} \cdot b \cdot f_{cd} \cdot (e - \frac{h - 0,8.d}{2})$$

Permissible normal force is given by:

$$N_{rd} = \frac{1}{e + z_s} x.b.f_{cd} (d - \frac{x}{2})$$

Permissible bending moment is provided by:

$$M_{rd} = M \cdot \frac{N_{rd}}{N}$$

Compression reinforcement is not taken to account.